

Chapter 3

An Introduction to

Finite Difference Calculus

Second Session Contents:

- 1) Taylor Table
- 2) difference methods from arbitrary order
- 3) Polynomial Finite Difference

Taylor Table

Second derivative

$$\left(\frac{\partial^2 u}{\partial x^2}\right)_j + \frac{1}{\Delta x^2}(au_{j-1} + bu_j + cu_{j+1}) = ?$$

u_j	$\left(\frac{\partial u}{\partial x}\right)_j \Delta x$	$\left(\frac{\partial^2 u}{\partial x^2}\right)_j \Delta x^2$	$\left(\frac{\partial^3 u}{\partial x^3}\right)_j \Delta x^3$	$\left(\frac{\partial^4 u}{\partial x^4}\right)_j \Delta x^4$
$\left(\frac{\partial^2 u}{\partial x^2}\right)_j \Delta x^2$	o	1	o	o
$a \cdot u_{j-1}$	$a \cdot (-1) \cdot \frac{1}{\Delta x}$	$a \cdot (-1)^2 \cdot \frac{1}{2}$	$a \cdot (-1)^3 \cdot \frac{1}{6}$	$a \cdot (-1)^4 \cdot \frac{1}{24}$
$b \cdot u_j$	b	o	o	o
$c \cdot u_{j+1}$	$c \cdot (1) \cdot \frac{1}{\Delta x}$	$c \cdot (1)^2 \cdot \frac{1}{2}$	$c \cdot (1)^3 \cdot \frac{1}{6}$	$c \cdot (1)^4 \cdot \frac{1}{24}$

$$cu_{j+1} = cu_j + c \cdot (1) \cdot \frac{1}{\Delta x} \cdot \left(\frac{\partial u}{\partial x}\right)_j + c \cdot (1)^2 \cdot \frac{1}{2} \Delta x^2 \cdot \left(\frac{\partial^2 u}{\partial x^2}\right)_j + c \cdot (1)^3 \cdot \frac{1}{6} \Delta x^3 \cdot \left(\frac{\partial^3 u}{\partial x^3}\right)_j + c \cdot (1)^4 \cdot \frac{1}{24} \Delta x^4 \cdot \left(\frac{\partial^4 u}{\partial x^4}\right)_j$$

Taylor Table

First derivative

$$\left(\frac{\partial u}{\partial x}\right)_j + \frac{1}{\Delta x}(au_{j-2} + bu_{j-1} + cu_j) = ?$$

u_j	$\left(\frac{\partial u}{\partial x}\right)_j \Delta x$	$\left(\frac{\partial^2 u}{\partial x^2}\right)_j \Delta x^2$	$\left(\frac{\partial^3 u}{\partial x^3}\right)_j \Delta x^3$	$\left(\frac{\partial^4 u}{\partial x^4}\right)_j \Delta x^4$
$\Delta x \cdot \left(\frac{\partial u}{\partial x}\right)_j$	o	1	o	o
$a \cdot u_{j-2}$	$a \cdot (-2) \cdot \frac{1}{\Delta x}$	$a \cdot (-2)^2 \cdot \frac{1}{2}$	$a \cdot (-2)^3 \cdot \frac{1}{6}$	$a \cdot (-2)^4 \cdot \frac{1}{24}$
$b \cdot u_{j-1}$	$b \cdot (-1) \cdot \frac{1}{\Delta x}$	$b \cdot (-1)^2 \cdot \frac{1}{2}$	$b \cdot (-1)^3 \cdot \frac{1}{6}$	$b \cdot (-1)^4 \cdot \frac{1}{24}$
$c \cdot u_j$	c	o	o	o

Obtaining difference methods from arbitrary order

$$\left(\frac{\partial^2 u}{\partial x^2}\right)_j + \frac{1}{\Delta x^2}(au_{j-1} + bu_j + cu_{j+1}) = ?$$

u_j	$\left(\frac{\partial u}{\partial x}\right)_j \Delta x$	$\left(\frac{\partial^2 u}{\partial x^2}\right)_j \Delta x^2$	$\left(\frac{\partial^3 u}{\partial x^3}\right)_j \Delta x^3$	$\left(\frac{\partial^4 u}{\partial x^4}\right)_j \Delta x^4$
$\left(\frac{\partial^2 u}{\partial x^2}\right)_j \Delta x^2$	o	1	o	o
$a \cdot u_{j-1}$	$a \cdot (-1) \cdot \frac{1}{\Delta x}$	$a \cdot (-1)^2 \cdot \frac{1}{2}$	$a \cdot (-1)^3 \cdot \frac{1}{6}$	$a \cdot (-1)^4 \cdot \frac{1}{24}$
$b \cdot u_j$	b	o	o	o
$c \cdot u_{j+1}$	$c \cdot (1) \cdot \frac{1}{\Delta x}$	$c \cdot (1)^2 \cdot \frac{1}{2}$	$c \cdot (1)^3 \cdot \frac{1}{6}$	$c \cdot (1)^4 \cdot \frac{1}{24}$

$$\begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix} \rightarrow [a, b, c] = [-1, -2, 1]$$

The columns whose summation is not zero, indicate the error value.

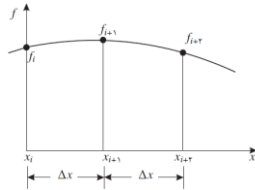
$$T.E. = \frac{1}{\Delta x^2} \left[\frac{a}{24} + \frac{c}{24} \right] \Delta x^4 \left(\frac{\partial^4 u}{\partial x^4}\right)_j = -\frac{\Delta x^2}{12} \left(\frac{\partial^4 u}{\partial x^4}\right)_j$$

Finite Difference by Polynomials

The second procedure for approximating a derivative is to represent the function as a polynomial. The coefficients of the polynomial are computed by substitution of data (dependent variable) from a series of usually equally spaced points of the independent variable.

For example, consider a second-order polynomial (shown in the figure below):

$$f(x) = Ax^{\tau} + Bx + C$$



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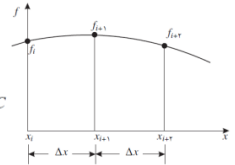
Finite Difference by Polynomials

Select the origin at x_i . Thus $x_i = 0$, $x_{i+1} = \Delta x$ and $x_{i+2} = \tau \Delta x$

$$f_i = Ax_i^{\tau} + Bx_i + C = C$$

$$f_{i+1} = Ax_{i+1}^{\tau} + Bx_{i+1} + C = A(\Delta x)^{\tau} + B(\Delta x) + C$$

$$f_{i+2} = Ax_{i+2}^{\tau} + Bx_{i+2} + C = A(\tau \Delta x)^{\tau} + B(\tau \Delta x) + C$$



From which it follows that:

$$C = f_i$$

$$B = \frac{-f_{i+2} + \tau f_{i+1} - \tau f_i}{\tau \Delta x}$$

$$A = \frac{f_{i+2} - \tau f_{i+1} + f_i}{\tau(\Delta x)^{\tau}}$$

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Finite Difference by Polynomials

Now computing the **first derivative**

$$\frac{\partial f}{\partial x} = \tau Ax + B$$

At $x_i = 0$

$$\left. \frac{\partial f}{\partial x} \right|_i = B \quad \longrightarrow \quad B = \frac{-f_{i+2} + \tau f_{i+1} - \tau f_i}{\tau \Delta x}$$

Therefore,

$$\frac{\partial f}{\partial x} = \frac{-f_{i+2} + \tau f_{i+1} - \tau f_i}{\tau \Delta x}$$

Which is identical to second-order accurate forward difference expression obtained from Taylor series.

The **second derivative** of function may be determined as:

$$\partial^2 f / \partial x^{\tau} = \tau A \quad \longrightarrow \quad A = \frac{f_{i+2} - \tau f_{i+1} + f_i}{\tau(\Delta x)^{\tau}}$$

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Finite Difference by Polynomials

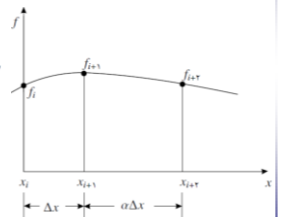
If the spacing of points $i, i+1$ and $i+2$ is not identical as shown in the figure, a finite difference approximation of the derivative is found by the same procedure.

Assume $x_i = 0$, $x_{i+1} = \Delta x$ and $x_{i+2} = (\nu + \alpha)\Delta x$ then

$$f_i = C$$

$$f_{i+1} = A(\Delta x)^{\nu} + B(\Delta x) + C$$

$$f_{i+2} = A(\nu + \alpha)^{\nu}(\Delta x)^{\nu} + B(\nu + \alpha)(\Delta x) + C$$



From which it follows that:

$$C = f_i$$

$$B = \frac{-f_{i+2} + (\nu + \alpha)^{\nu} f_{i+1} - (\alpha^{\nu} + \nu \alpha) f_i}{\alpha(\nu + \alpha)\Delta x}$$

$$A = \frac{f_{i+2} - (\nu + \alpha)^{\nu} f_{i+1} + \alpha f_i}{\alpha(\nu + \alpha)(\Delta x)^{\nu}}$$

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Finite Difference by Polynomials

Now computing the **first derivative** of function, one has

At $x_i = 0$

$$\frac{\partial f}{\partial x} = \tau Ax + B$$

$$\left. \frac{\partial f}{\partial x} \right|_{x_i} = B \quad \rightarrow \quad B = \frac{-f_{i+\tau} + (\lambda + \alpha)^\tau f_{i+\lambda} - (\alpha^\tau + \tau\alpha) f_i}{\alpha(\lambda + \alpha)\Delta x}$$

Therefore,

$$\left. \frac{\partial f}{\partial x} \right|_{x_i} = \frac{-f_{i+\tau} + (\lambda + \alpha)^\tau f_{i+\lambda} - \alpha(\alpha + \tau) f_i}{\alpha(\lambda + \alpha)\Delta x}$$

The **second derivative** of function can be determined as:

$$\partial^2 f / \partial x^2 = \tau A \quad \rightarrow \quad A = \frac{f_{i+\tau} - (\lambda + \alpha) f_{i+\lambda} + \alpha f_i}{\alpha(\lambda + \alpha)(\Delta x)^2}$$

Therefore,

$$\frac{\partial^2 f}{\partial x^2} = \tau \left[\frac{f_{i+\tau} - (\lambda + \alpha) f_{i+\lambda} + \alpha f_i}{\alpha(\lambda + \alpha)(\Delta x)^2} \right]$$

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Example

Determine the approximate forward difference representation for $\partial^2 f / \partial x^2$ which is of the order Δx , by means of

A) Taylor series expansion
B) A third-degree polynomial passing through four points

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Solution

A) Taylor series expansions

$$\begin{aligned} f(x + \Delta x) &= f(x) + \Delta x \frac{\partial f}{\partial x} + \frac{(\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + O(\Delta x)^4 \\ f(x + \tau\Delta x) &= f(x) + \tau\Delta x \frac{\partial f}{\partial x} + \frac{(\tau\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\tau\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + O(\tau\Delta x)^4 \\ f(x + \lambda\Delta x) &= f(x) + \lambda\Delta x \frac{\partial f}{\partial x} + \frac{(\lambda\Delta x)^2}{2!} \frac{\partial^2 f}{\partial x^2} + \frac{(\lambda\Delta x)^3}{3!} \frac{\partial^3 f}{\partial x^3} + O(\lambda\Delta x)^4 \end{aligned}$$

The three simultaneous equations can be solved for $\partial^2 f / \partial x^2$

Then:

$$\frac{\partial^2 f}{\partial x^2} = \frac{f_{i+\tau} - \tau f_{i+\lambda} + \tau f_{i+\lambda} - f_i}{(\Delta x)^2} + O(\Delta x)$$

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Solution

B) Fitting the third-degree polynomial $f(x) = Ax^3 + Bx^2 + Cx + D$ through the four equally spaced points. One can obtain:

$$\begin{aligned} f_{i+\tau} &= A(\tau\Delta x)^3 + B(\tau\Delta x)^2 + C(\tau\Delta x) + D \\ f_{i+\lambda} &= A(\lambda\Delta x)^3 + B(\lambda\Delta x)^2 + C(\lambda\Delta x) + D \\ f_{i+\tau} &= A(\Delta x)^3 + B(\Delta x)^2 + C(\Delta x) + D \\ f_i &= D \end{aligned}$$

From which it follows that:

$$C = \frac{\tau f_{i+\tau} - \tau f_{i+\lambda} + \lambda f_{i+\lambda} - \lambda f_i}{\tau\Delta x}$$

$$B = \frac{-\tau f_{i+\tau} + \lambda f_{i+\tau} - \lambda f_{i+\lambda} + f_i}{\tau(\Delta x)^2} \quad D = f_i$$

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Solution

Now, the derivative of $f(x)$ are determined as

$$\frac{\partial f}{\partial x} = \tau Ax^r + \tau Bx + C, \quad \frac{\partial^2 f}{\partial x^2} = \tau Ax + \tau B, \quad \frac{\partial^3 f}{\partial x^3} = \tau A$$

Therefore,

$$\frac{\partial^2 f}{\partial x^2} = \frac{f_{i+\tau} - \tau f_{i+\tau} + \tau f_{i+\lambda} - f_i}{(\Delta x)^2} + O(\Delta x)$$

In addition, the first and second derivatives at i , where x is zero, are obtained easily as

$$\frac{\partial^2 f}{\partial x^2} = \tau B = \frac{-f_{i+\tau} + \tau f_{i+\tau} - \Delta f_{i+\lambda} + \tau f_i}{(\Delta x)^2} + O(\Delta x)^2$$

$$\frac{\partial f}{\partial x} = C = \frac{\tau f_{i+\tau} - \tau f_{i+\tau} + \lambda \tau f_{i+\lambda} - \lambda f_i}{\tau \Delta x} + O(\Delta x)^2$$

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Example

Determine a central difference approximation $\partial f / \partial x$ for the unequally spaced grid points by polynomial technique.

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Solution

The second-order polynomial is passed through the points $x_i = 0, x_{i+1} = \alpha \Delta x$ and $x_{i-1} = -\Delta x$

Thus, $f_{i-1} = A(-\Delta x)^2 + B(-\Delta x) + C$

$$f_i = C$$

$$f_{i+1} = A(\alpha \Delta x)^2 + B(\alpha \Delta x) + C$$

Solving for the coefficients A, B and C, one finds

$$A = \frac{f_{i+1} - (\alpha + 1)f_i + \alpha f_{i-1}}{\alpha(\alpha + 1)(\Delta x)^2}$$

$$B = \frac{f_{i+1} + (\alpha^2 - 1)f_i - \alpha^2 f_{i-1}}{\alpha(\alpha + 1)(\Delta x)}$$

$$C = f_i$$

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Solution

The first derivative of the function is

$$\frac{\partial f}{\partial x} = \tau Ax + B$$

Which at point x_i reduces to B. Therefore,

$$\frac{\partial f}{\partial x} = \frac{f_{i+1} + (\alpha^2 - 1)f_i - \alpha^2 f_{i-1}}{\alpha(\alpha + 1)(\Delta x)} + O(\Delta x)^2$$

Note that for $\alpha = 1$ the expression reduces to $\frac{\partial f}{\partial x} = \frac{f_{i+1} - f_{i-1}}{2(\Delta x)} + O(\Delta x)^2$

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